Stroke 1.97 (IP65)



Approx. weight: 22.1 lb without accessories

Stroke 2.56 (IP67)


Approx. weight: 26.5 lb without accessories

## Positioner

 integrated
## 1798 lbf

Max. thrust $)^{1}$

## 84.7-36.2 Secs/In.

 Stroke Speed Stroke 1.97 In . opt. 2.56 In .Modulating actuator Class C acc. to DIN EN ISO 22153
Enclosure IP65
EN 60529

| Stroke Speed |  |
| :--- | :--- |
| Power supply | [V] |
| Nominal current ) | $[$ [A] |
| Max. current $)^{4}$ | $[\mathrm{~A}]$ |
| Power consumption $)^{5}$ | $[\mathrm{~W}]$ |


| 84.7-36.2 Secs/In. (adjustable) |  |  |  |
| :---: | :---: | :---: | :---: |
| 230 VAC 1~ | 115 VAC 1~ | 24 VAC/DC | 360...575 VAC 3~ ) |
| 0.22 | 0.44 | $2.1(\mathrm{AC}) / 1.3(\mathrm{DC})$ | $0.18)^{3}$ |
| 0.29 | 0.57 | $2.7(\mathrm{AC}) / 1.7(\mathrm{DC})$ | $0.23)^{3}$ |
| 38 | 38 | $35(\mathrm{AC}) / 32(\mathrm{DC})$ | $47)^{3}$ |


| Standard | Description |
| :---: | :---: |
| Ambient temperature [ ${ }^{\circ} \mathrm{F}$ ] | $-4^{\circ} \mathrm{F}$ to $+140^{\circ} \mathrm{F}$ |
| Motor protection | Electronic motor current monitoring with safety cut-off |
| Overvoltage category | II |
| Break away force | Adjustable up to +50\% nominal force |
| Duty cycle as periEC 60034-1,8 | S2 30 min S4 50\% ED @ $77^{\circ} \mathrm{F}$ |
| Control signal and feedback | 0 (4).. 20 mA or 0 (2).. 10 V selectable, split range operation |
| Binary control | $24 \mathrm{~V}-230 \mathrm{~V}$ for ON/OFF control (min. duration of pulse 1s) |
| Valve positioner function | Integrated, deadband adjustable from 0.5 .. 5\%, shut-off MIN |
| Automatic start-up | Recognizing the end position(s) and autoscaling set and feedback values |
| Internal fault monitoring | Thrust, control signal, temperature, power supply |
| Fault indication relay FIR | Standard, potential-free opening contact provides a freely definable (programmable) collective fault signal and doubles for indication for when optional Local Controls is NOT in remote mode |
| Diagnostics function | Stores cumulated operation data (motor and total running time, number of motor starts) and data sets of current values (set value, feedback value, torque, temperature and error messages) |
| Communication interface | Connecting to a USB port and a software, allows data reading and parametrisation |
| Conduit entries | $2 \mathrm{pcs}$. M $20 \times 1,5$ and $1 \mathrm{pcs} . \mathrm{M} 16 \times 1,5$ |

$)^{1}=$ permissible average force over the entire travel is $50 \%$ of the max. thrust
$)^{2}=$ max. input voltage range
$)^{3}=$ at $400 \vee 3^{\sim}$ and 50 Hz
$)^{4}=$ data may vary depending on accessories
$)^{5}=$ at max. thrust, data may vary depending on accessories

PSL208 AMS11

## Technical Data

## Wiring Termination



## Dimensions of the PS Standard Adaptation



Connection Thread X

| M8 | Optional |
| :--- | :--- |
| M10 | Optional |
| M12 | Optional |
| M14 | Optional |
| M16 | Standard |

Fine threaded and other sizes on request!

## Mounting Position



2 potential-free position switches, mechanical, with silverplated changeover contacts, 24 V to $230 \mathrm{~V} \mathrm{AC/DC} @ 0.1 \mathrm{~A}-5 \mathrm{~A}$
2 potential-free position switches, mechanical, with gold-plated changeover contacts
5 V to $30 \mathrm{~V} \mathrm{AC/DC} @ 1 \mathrm{~mA}-100 \mathrm{~mA}$; contact resistance 30 mOhm Enables the autonomous control of a process so that an external controller is not required.
Emergency power supply based on supercapacitors, safety position OPEN, CLOSED or free defined position
Digital transmission of nominal and actual value per mill or percent, report of monitoring and diagnostic data using Profibus DP (PSPDP) or CANOpen (PSCA) interfaces, additional interfaces available on request Illuminated display to show the actuator status and lockable selector to switch between modes: automatic, manual process ON/OFF, STOP and parameter menu. Control buttons for manual movement, menu operation and adjustment of parameters, display of diagnostic information
Mounting separately from the actuator (incl. 10 m connection cable)
USB data cable enables the communication between the actuator and a PC by using the software PSCS
Signal port to drive to a "safety position", selectable fail-safe position, standard 24 230 V
Increased enclosure IP67
Heating resistor to prevent condensation
*not retrofittable
For more information and accessories, please visit our website www.ps-automation.com!
Subject to changes!

